

Resource-efficient welding processes through numerical simulation and optimization

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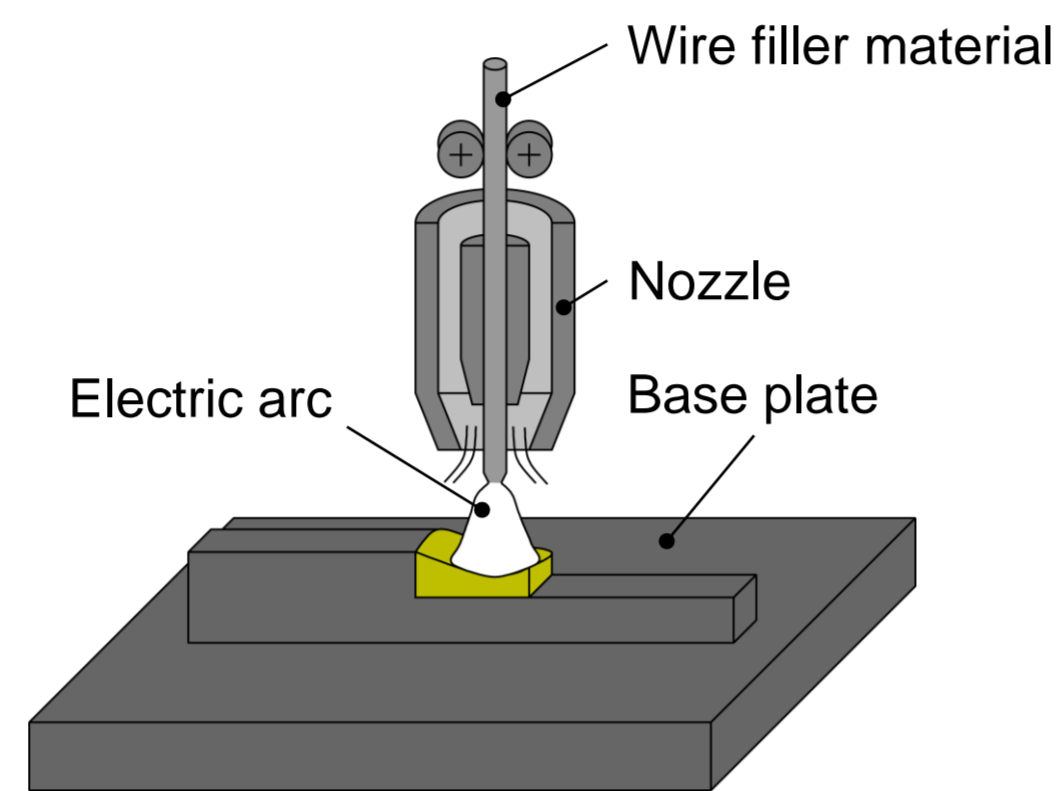
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Scope

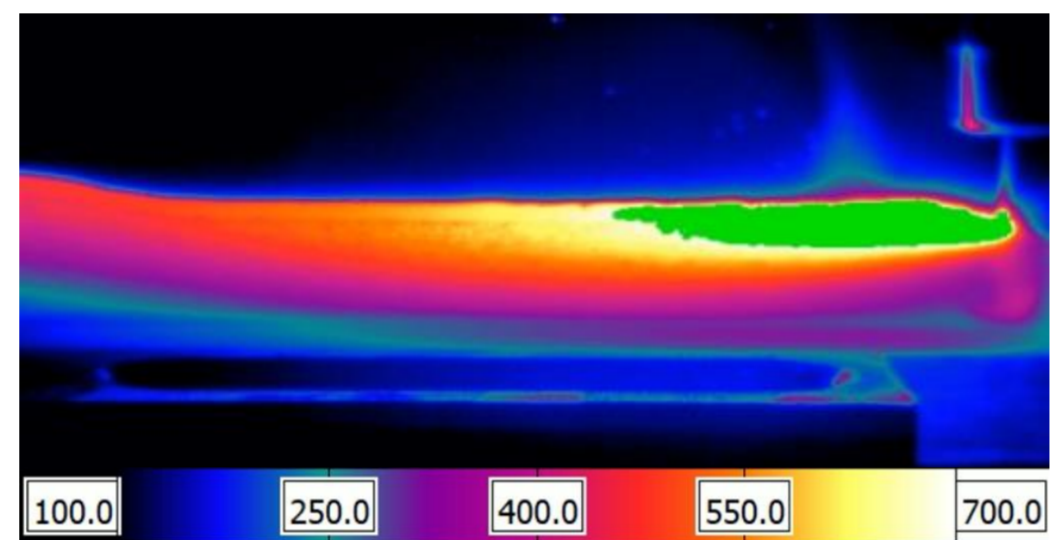
Wire arc additive manufacturing

- High deposition rates
- Small cooling rates
- High energy input
- Multi-material design



Cooling times required to prevent overheating of the structure

- Usually chosen based on experience
- Lack of reproducibility
- Unwanted part properties
- Extended process time



→ Provide a numerical tool for process parameter optimization

- Cooling time
- Welding velocity

Optimization Problem

Transient heat conduction equation

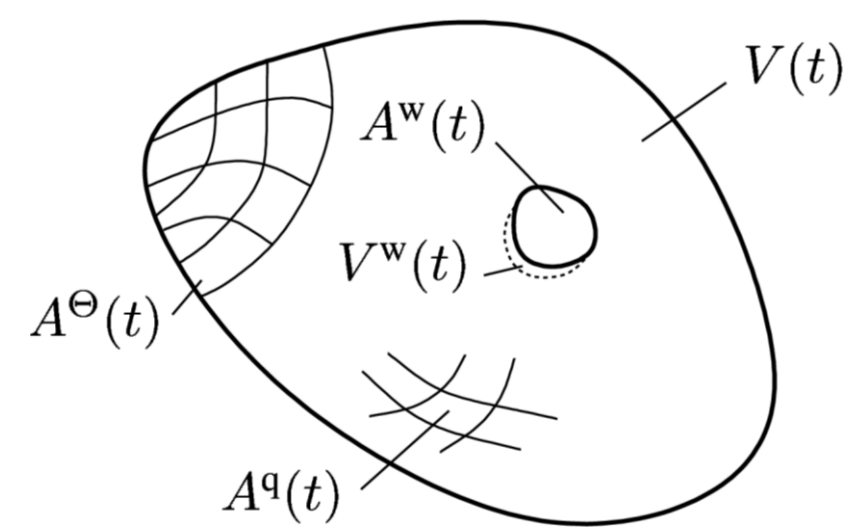
$$\rho(\vec{x})c_p(\Theta)\dot{\Theta}(\vec{x}, t) = -\text{div} \vec{q}(\vec{x}, t) + r_{\Theta}(\vec{x}, t)$$

Constitutive equation (Fourier's model)

$$\vec{q}(\vec{x}, t) = -\kappa(\Theta) \text{grad} \Theta(\vec{x}, t)$$

Boundary and initial conditions

$$\begin{aligned} \Theta(\vec{x}, t) &= \bar{\Theta}(\vec{x}, t) && \text{on } A^{\Theta}(t) \\ \vec{q}(\vec{x}, t) \cdot \vec{n}(\vec{x}) &= \hat{q}(\vec{x}, t) && \text{on } A^w(t) \\ \vec{q}(\vec{x}, t) \cdot \vec{n}(\vec{x}) &= \bar{q}(\Theta(\vec{x}, t)) && \text{on } A^q(t) \\ \Theta(\vec{x}, t_0) &= \Theta_0(\vec{x}) && \text{at } t_0 \end{aligned}$$



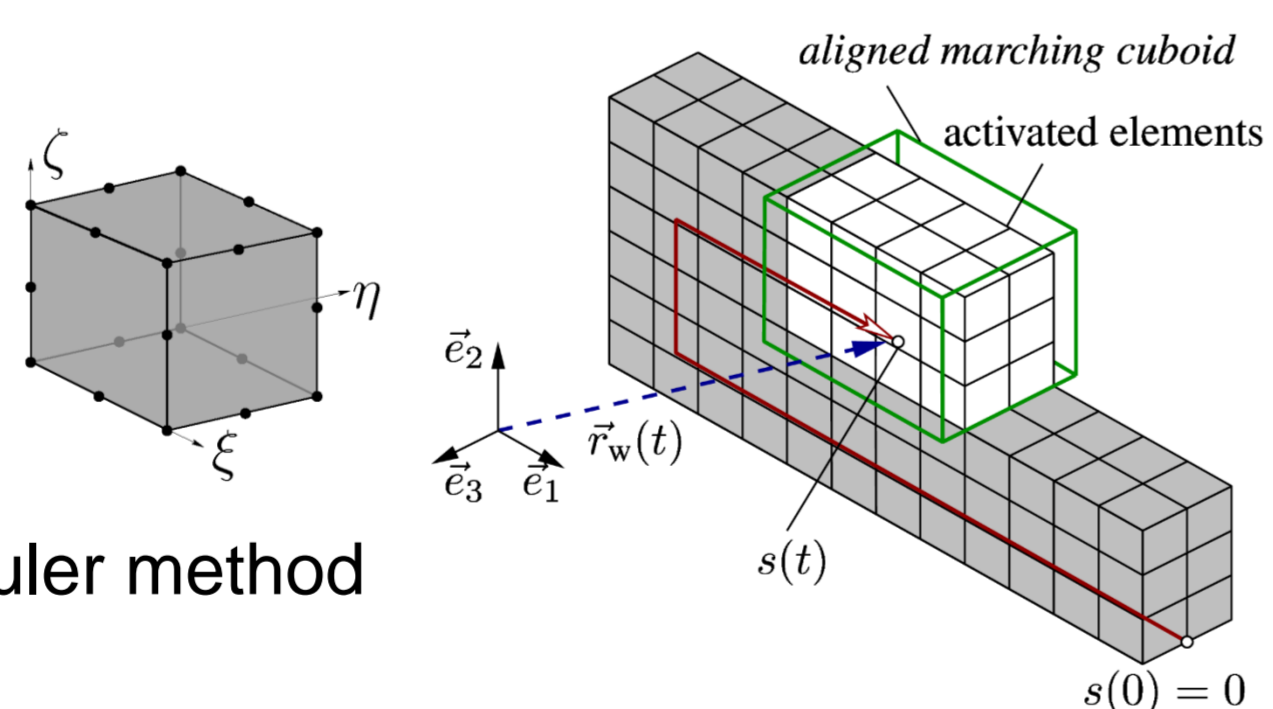
Convection and non-linear radiation

$$\vec{q}(\Theta) = h(\Theta)(\Theta - \Theta_{\infty}) + \sigma\epsilon(\Theta)(\Theta^4 - \Theta_{\infty}^4)$$

→ Geometry evolves during the process

Spatial discretization with finite elements

$$\vec{g} \left(t_{n+1}, \Theta_{n+1}, \frac{\Theta_{n+1} - \Theta_n}{\Delta t_n} \right) = \mathbf{0}$$

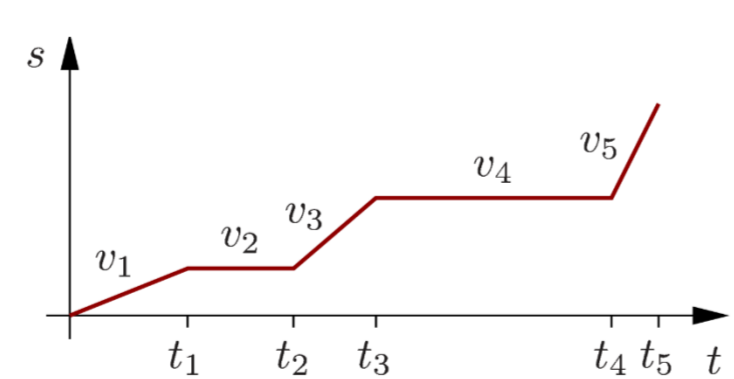


Temporal discretization with Backward Euler method

→ Inactive element method (element activation → non-smooth model response)

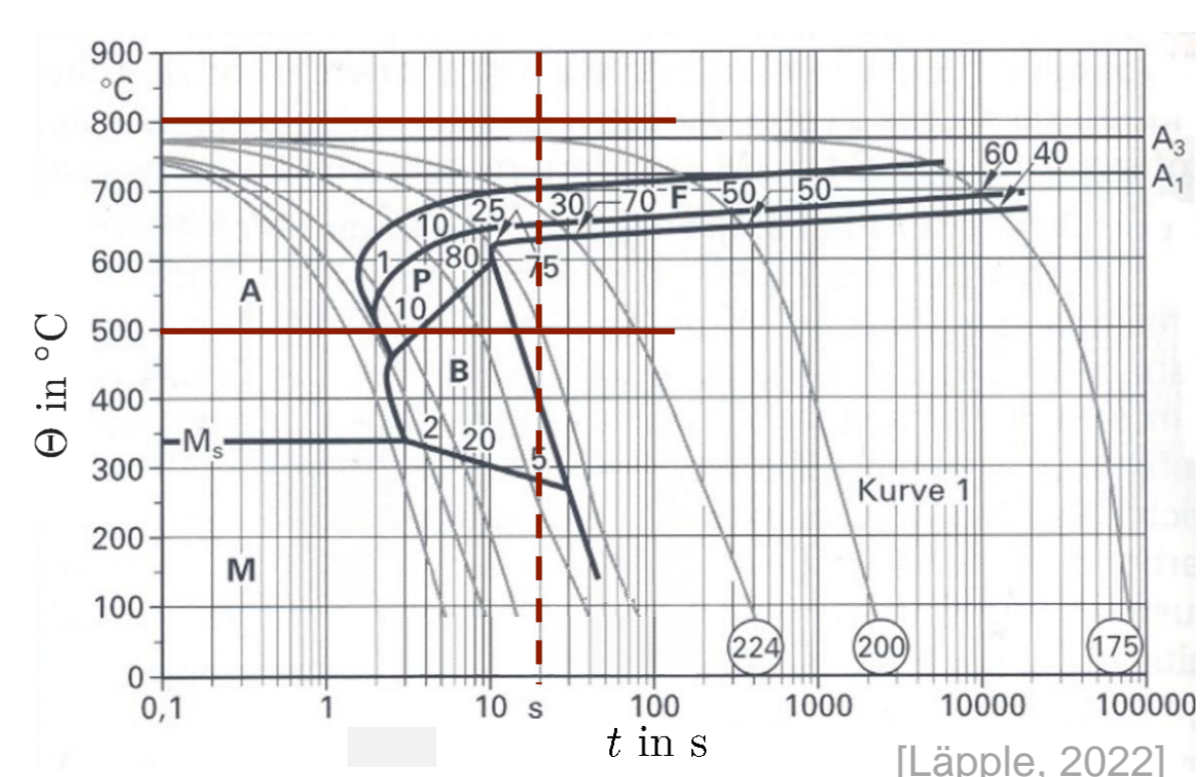
Goal: Minimize process time

$$\min_{\kappa} T(\kappa) \quad \text{i.e.} \quad \kappa^* = \arg \min_{\kappa} T(\kappa)$$



Process related inequality constraints

- Welding velocity
 $v_w(t) \geq v_{w,\min}, \quad v_w(t) \leq v_{w,\max}$
- Cooling time (process)
 $\Delta t_c \geq 0$
- Cooling time (structure)
 $\Delta t_{s/5} \leq \Delta t_{s/5,\max}$
- Interlayer temperature
 $\Theta_{\text{int}} \leq \Theta_{\text{int},\max}$



→ Gradient-free optimization using Nelder-Mead Simplex algorithm

Reference: Tröger, J.-A., Hartmann, S., Treutler, K., Potschka, A., Wesling, V.: Simulation-based process parameter optimization for wire arc additive manufacturing. Submitted to Progress in Additive Manufacturing

Model Calibration

Model calibration using non-linear least-squares method

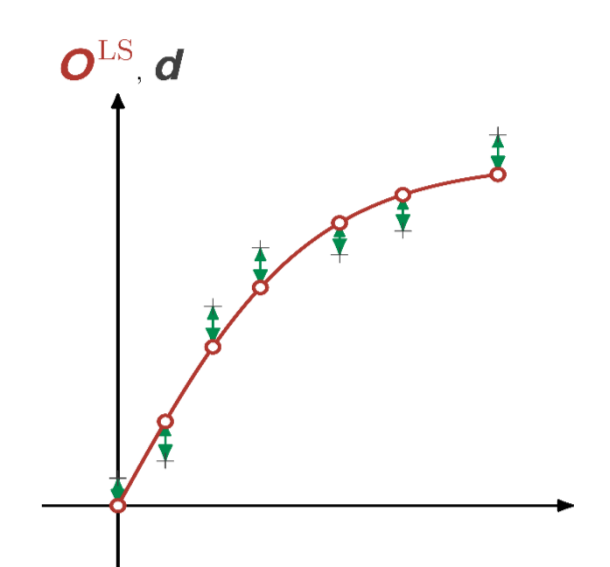
$$f(\beta) = \frac{1}{2} \|r(\beta)\|^2 \quad \min_{\beta} f(\beta) \quad \text{i.e.} \quad \beta^* = \arg \min_{\beta} f(\beta)$$

$$\text{Residuum} \quad r(\beta) = \mathbf{O}^{\text{LS}}(\mathbf{S}^{\text{LS}}(\beta)) - \mathbf{d}$$

$$\text{Experimental data} \quad \mathbf{d}$$

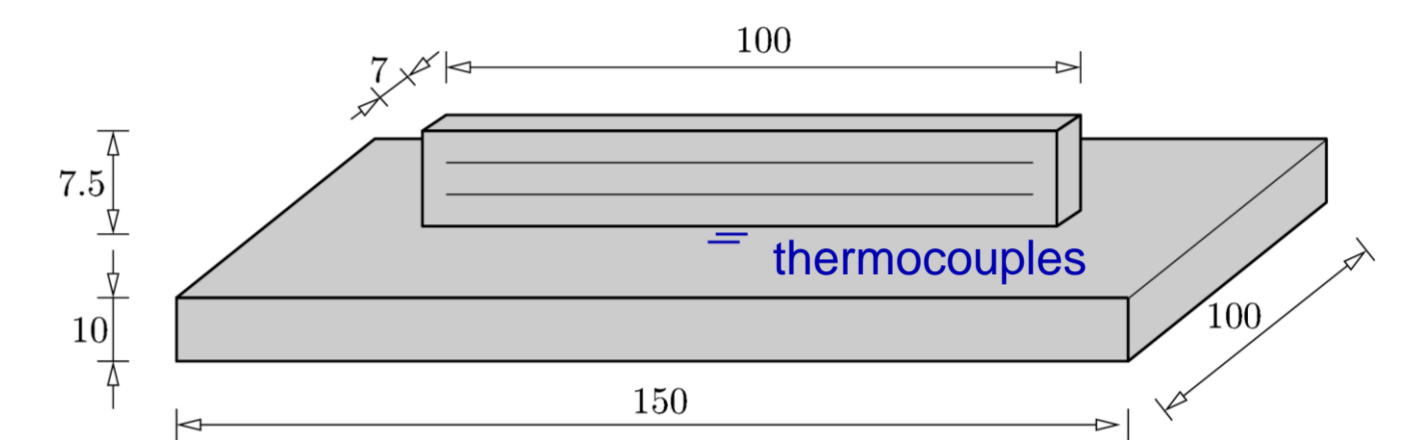
$$\text{Model response} \quad \mathbf{O}^{\text{LS}}(\mathbf{S}^{\text{LS}}(\beta)) \quad \rightarrow \text{Finite element simulation}$$

$$\text{Parameters} \quad \beta = \{c_1, c_2, c_3\}^T$$



Experimental setup – three-layered vertical wall

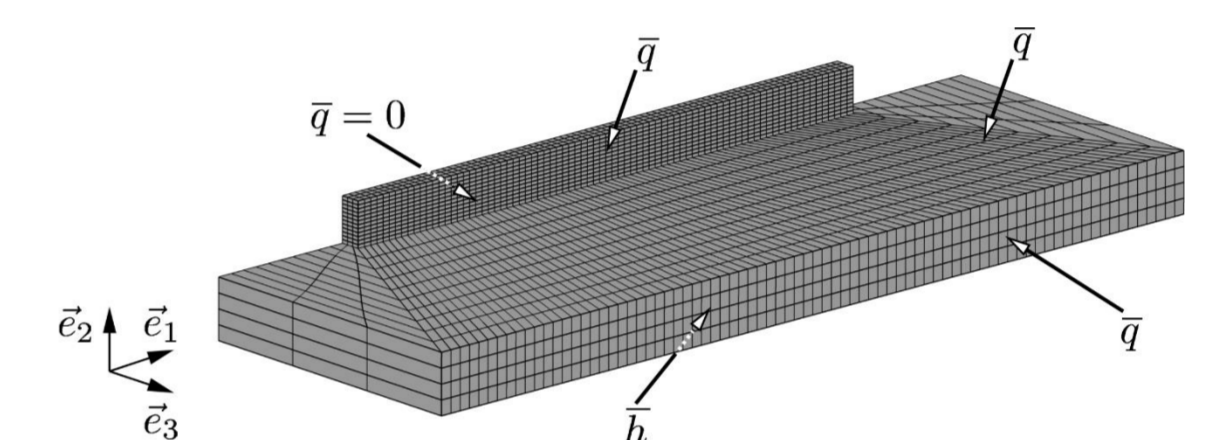
arc voltage	arc current	wire feed rate	welding velocity
17.7 V	147.7 A	4 m/min	50 cm/min



Numerical model

- Symmetry in \vec{e}_3 -direction
- Goldak's double ellipsoidal heat source
- Ansatz for convection on free surfaces

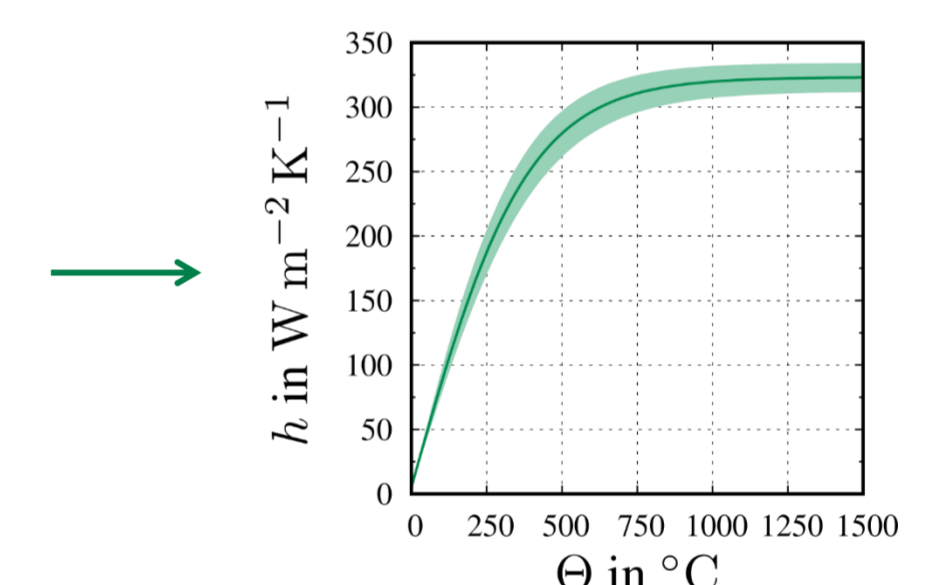
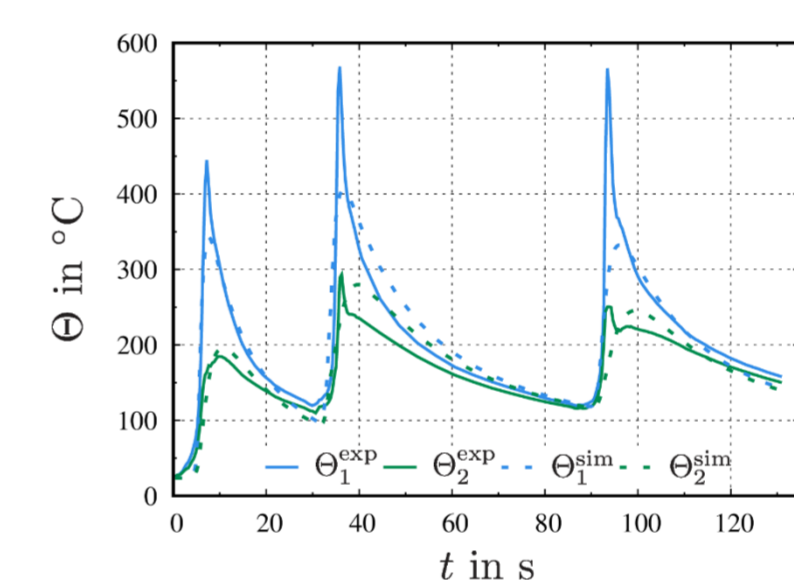
$$h(\Theta) = c_1 \tanh(c_2 \Theta) + c_3$$



Calibration result and uncertainty quantification

→ 77 finite element simulations required during calibration

parameter	value ± uncert.	dimension
c_1	318 ± 11	$\text{W m}^{-2} \text{K}^{-1}$
c_2	$2.6 \times 10^{-3} \pm 2 \times 10^{-4}$	$^{\circ}\text{C}$
c_3	5.2 ± 0.6	$\text{W m}^{-2} \text{K}^{-1}$



Results

Penalty objective function for process parameter optimization

$$\hat{f}(\kappa) = w_t \sum_{i=1}^{n_1} \underbrace{(\Delta t_w^{(i)} + \Delta t_c^{(i)})}_{\text{welding and cooling time per layer}} + p \underbrace{(\Delta t_{w,\min} - \Delta t_w^{(i)})}_{\text{constraint max. welding velocity}} + p \underbrace{(\Delta t_w^{(i)} - \Delta t_{w,\max})}_{\text{constraint min. welding velocity}} + p \underbrace{(-\Delta t_c^{(i)})}_{\text{constraint positive cooling time}} + p \underbrace{(O_{s/5}^{(i)}(\mathbf{S}(\kappa)) - \Delta t_{s/5,\max})}_{\text{constraint layer cooling}} + w_{\Theta} p \sum_{j=1}^{n_1-1} \underbrace{(O_{\text{int}}^{(j)}(\mathbf{S}(\kappa)) - \Theta_{\text{int},\max})}_{\text{constraint interlayer temperature}} \quad (x) = \begin{cases} 0 & \text{if } x < 0, \\ x & \text{if } x \geq 0 \end{cases}$$

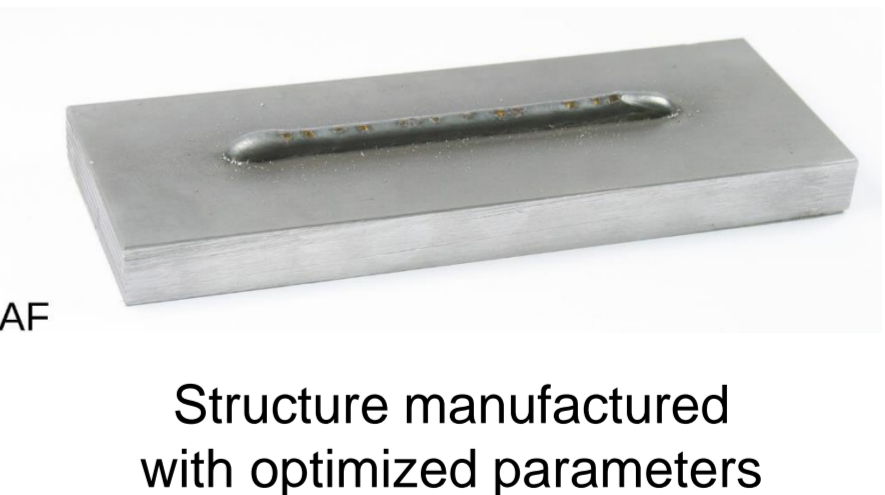
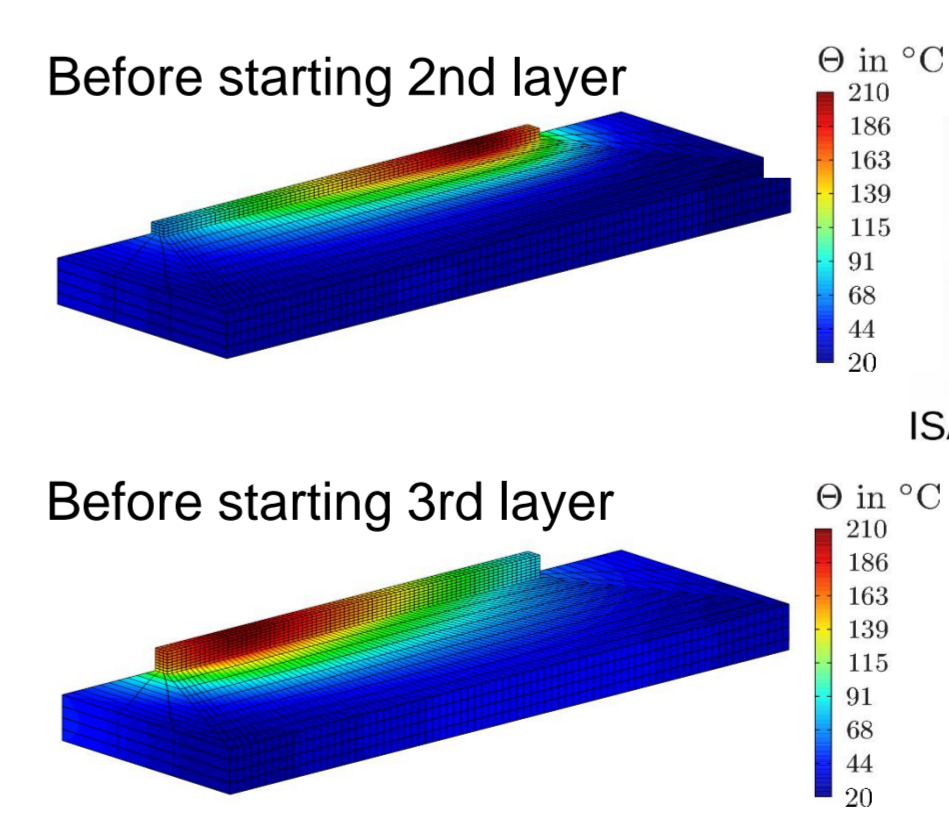
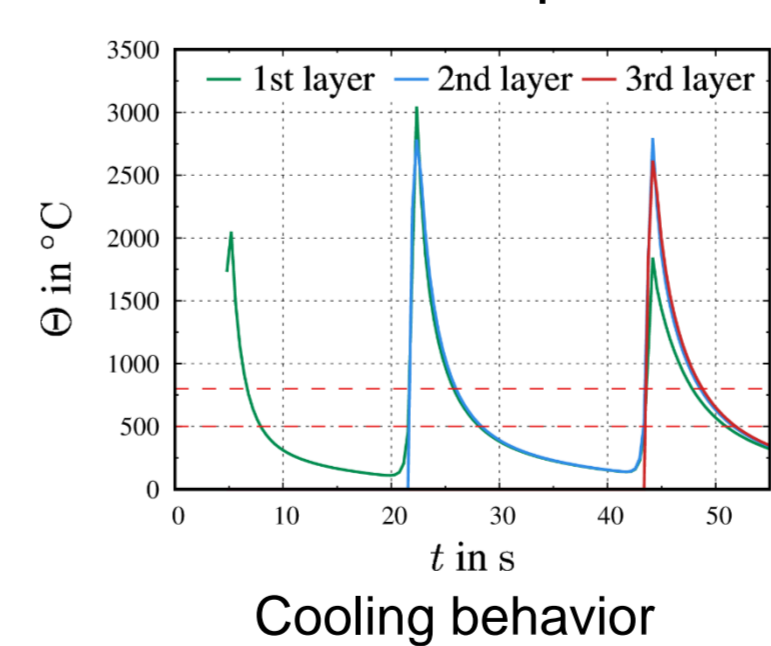
Parameters $\kappa = \{\Delta t_w^{(i)}, \Delta t_c^{(i)}\}^T$
Weighting factors $w_t = \text{s}^{-1}, w_{\Theta} = ^{\circ}\text{C}^{-1}$
Penalty factor p

$v_{w,\min}$	$v_{w,\max}$	$\Delta t_{s/5,\max}$	$\Theta_{\text{int},\max}$
5 mm s ⁻¹	10 mm s ⁻¹	20 s	180 °C

Process parameter optimization – three-layered vertical wall

Optimized parameters $\Delta t_w^{(1)} = 10 \text{ s}, \Delta t_w^{(2)} = 14.4 \text{ s}, \Delta t_w^{(3)} = 13.2 \text{ s}, \Delta t_c^{(1)} = 5.1 \text{ s}, \Delta t_c^{(2)} = 7.9 \text{ s}$
Welding velocities $v_w^{(1)} = 10 \text{ mm s}^{-1}, v_w^{(2)} = 6.95 \text{ mm s}^{-1}, v_w^{(3)} = 7.56 \text{ mm s}^{-1}$
Cooling time $\Delta t_{s/5}^{(i)} \approx 3 \text{ s}, i = 1, 2, 3$
Interlayer temperature $\Theta_{\text{int}}^{(1)} = 174 ^{\circ}\text{C}, \Theta_{\text{int}}^{(2)} = 180 ^{\circ}\text{C}$

→ 124 finite element simulations required



- Optimized parameters satisfy process- and material-related constraints
- Process time reduced by 48% compared to manually chosen parameters

Outlook

- Extension to variable arc voltage and arc current within optimization
- Control energy input during process
- Further development of modelling capabilities
 - Heat source model
 - Complex welding paths